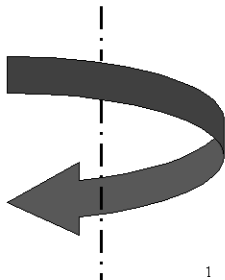


Chapter 11

Kinematics:
Angular Motion



Miami University

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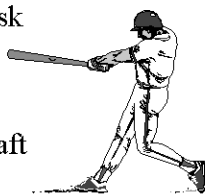
Objectives

- Angular Displacement (rads)
- Angular Velocity (rpm, or rads/s)
- Angular Acceleration (rads/s²)
- All based on equations similar to Rectilinear Motion

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Angular Motion

- Any body that rotates about a point undergoes angular motion
 - Rotating a pulley or disk
 - Swinging a bat
 - Spinning a propeller
 - Rotation of a motor shaft



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Angular Displacement

- A lever rotates one quarter of a turn – angular displacement is 90 degrees
- Measured in radians
 - There are 2π radians in 360°
- $90^\circ = 2\pi / 4 = 1.57 \text{ rad}$
- Note calculators degrees vs radians



4

Angular Velocity

- Rate of change of angular disp.
- $\omega = \Delta\theta/\Delta t$
- Omega = rad/s, rpm or rev/min
- Rarely determined in degrees/s
- 1000 revs in 600 sec = 100 rpm



$$100 \frac{\text{rev}}{\text{min}} \times \frac{1 \text{ min}}{60 \text{ s}} \times \frac{2\pi \text{ rad}}{1 \text{ rev}} = 10.47 \text{ rad/s}$$

5

Angular Acceleration

- Rate of change of angular velocity is the letter alpha (α)
- Acceleration is in rad/s²

$$\alpha = \frac{\Delta\omega}{\Delta t} = \frac{\omega_2 - \omega_1}{t_2 - t_1}$$

6

Angular motion with uniform acceleration

- Use the same equations as we used in rectilinear motion
- Substitute θ , ω , α for s , v , a
- Remember that these equations are based on uniform acceleration

7

Equations

$$\begin{array}{l|l} s = s_0 + v_0t + \frac{1}{2}at^2 & \theta = \theta_0 + \omega_0t + \frac{1}{2}\alpha t^2 \\ v = v_0 + at & \omega = \omega_0 + \alpha t \\ v^2 = v_0^2 + 2as & \omega^2 = \omega_0^2 + 2\alpha\theta \end{array}$$

8

Units

- When determining angular motion, be sure to change everything to radians and seconds.

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Week 4 Homework

- Chapter 11
 - 7, 8, 12, 15, 20, 21 & 24
 - Read Section 11-6 & 11-7
 - Quiz No. 1 next week over Chapters 9 & 10

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